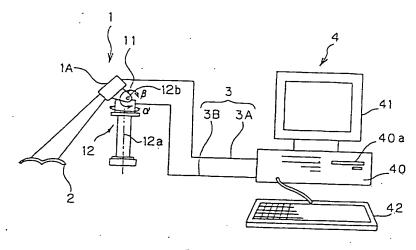
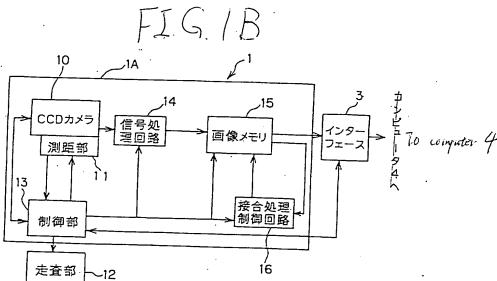
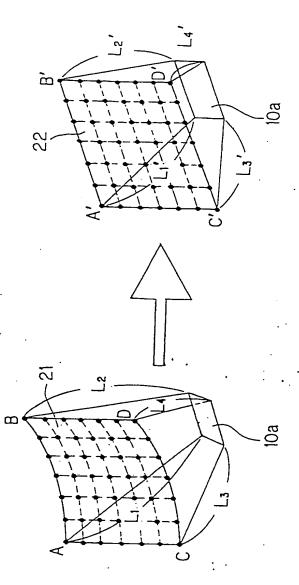


### FIG. 1A



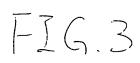


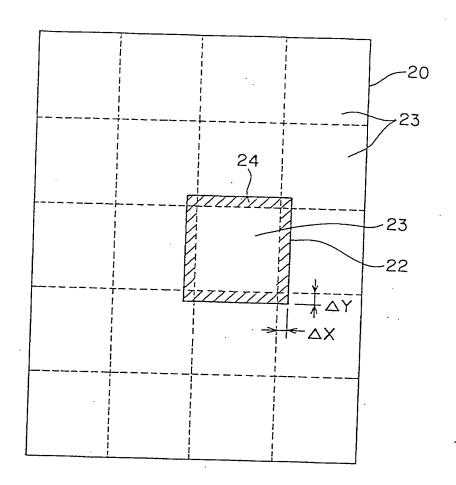
- 3: interface
- 10: CCD camera
- 11: distance measurement unit
- 12: scanner
- 13: controller
- 14: signal processor
- 15: image memory
- 16: synthesization controller



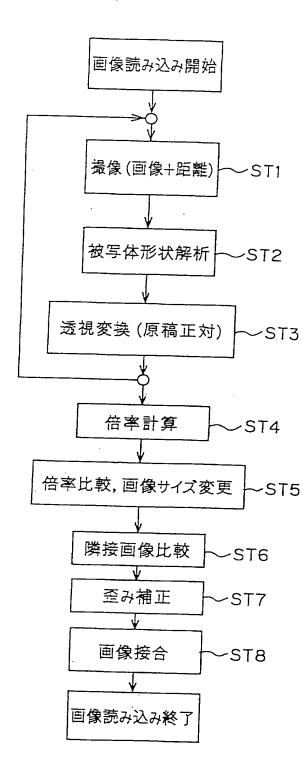
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# FIG. 4



Start image reading

ST1: Acquire image (image + distance).

ST2: Analyze shape of object.

ST3: Perspective transformation (positive document pair)

ST4: Calculate magnification rates.

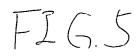
ST5: Compare magnification rates and change image sizes.

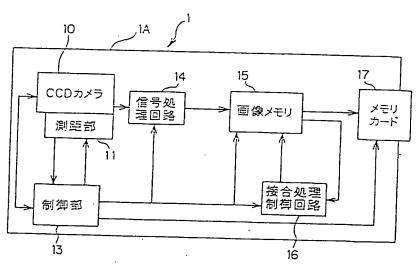
ST6: Compare adjacent images.

ST7: Correct distortion.

ST8: Synthesize images.

End image reading





10: CCD camera

11: distance measurement unit

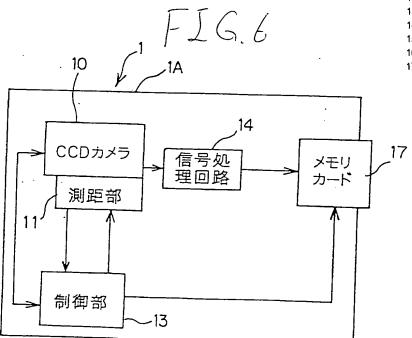
13: controller

14: signal processor

15: image memory

16: synthesization controller

17: memory card



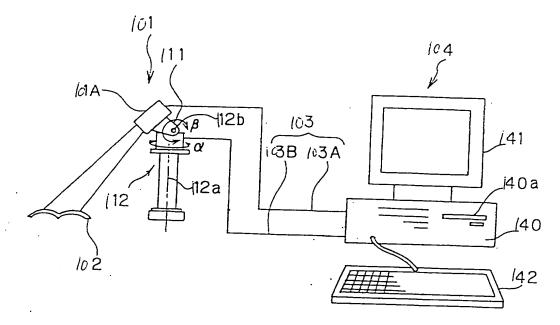
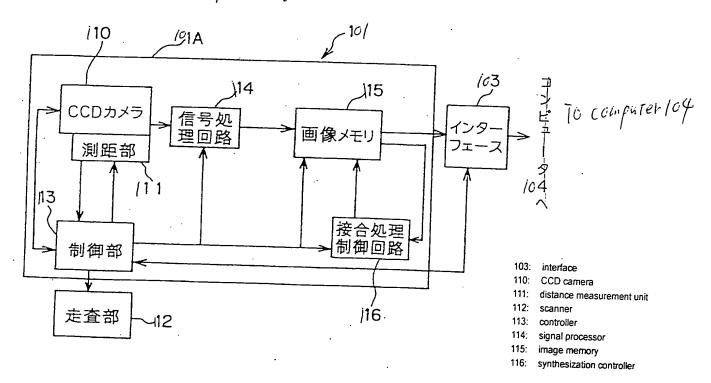
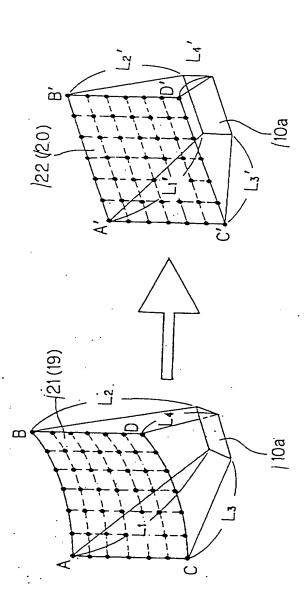
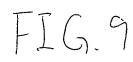
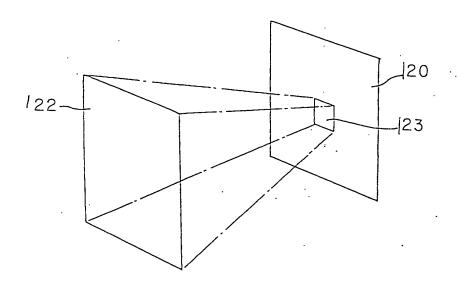


FIG. 1B

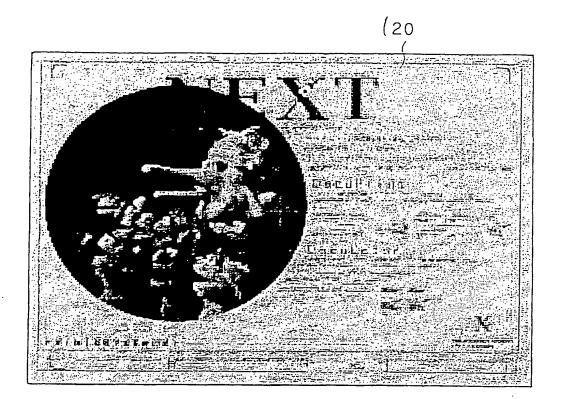


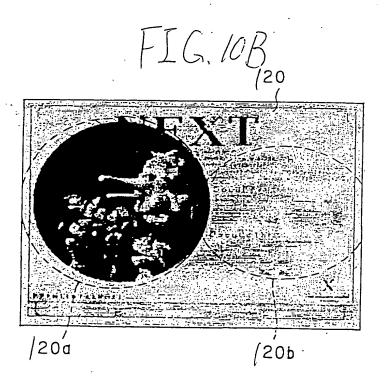






## FIG. 10A





### FIG. //A

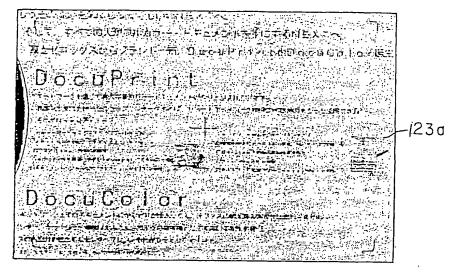


FIG. 11B

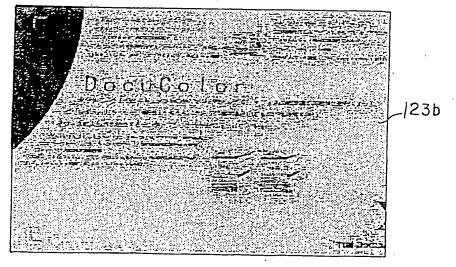
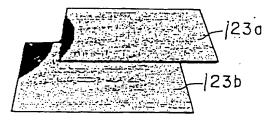


FIG. 11C



#### FIG. 12A



#### FIG. 12B

